

qnetworks

A Queueing Networks Analysis Package for GNU Octave
User's Guide, Edition 1 for release 0.8.4
2010-06-23

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This is the first edition of the `qnetworks` documentation, and is consistent with version 0.8.4 of the package.

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1 Preface

This document describes the `qnetworks` package; `qnetworks` is a collection of functions written in GNU Octave which implement numerical algorithms for analyzing Queueing Network models. In particular, the `qnetworks` package contains functions for analyzing Jackson networks, open, closed or mixed product-form BCMP networks, and computation of performance bounds. More specifically, the following algorithms have been implemented

- Convolution for closed, single-class product-form networks with load-dependent service centers;
- Mean Value Analysis (MVA) algorithms for single as well as multiple-class closed product-form networks.
- MVA for mixed, multiple class product-form networks with load-independent service centers;
- Closed, single-class networks with blocking using the approximate MVABLO algorithm by F. Akyildiz;
- Closed, multiple class product-form networks using approximate MVA (Bard-Schweitzer approximation);
- Computation of Asymptotic Bounds, Balanced System Bounds as well as Geometric Bounds;

Furthermore, `qnetworks` provides functions for analyzing the following kind of single-station queueing systems:

- $M/M/1$
- $M/M/m$
- $M/M/\infty$
- $M/M/1/k$ single-server, finite capacity system
- $M/M/m/k$ multiple-server, finite capacity system
- Asymmetric $M/M/m$
- $M/G/1$ (general service time distribution)
- $M/H_m/1$ (Hyperexponential service time distribution)

Finally, functions for Markov Chain analysis are provided as well:

- Birth-death process;
- Computation of mean time to absorption;
- Computation of time-averages sojourn time.

`qnetworks` is distributed under the terms of the GNU General Public License (GPL), version 3 or later (see [Appendix C \[Copying\], page 53](#)) You are encouraged to share this software with others, and make this package more useful by contributing additional functions and reporting problems. See [Appendix A \[Contributing Guidelines\], page 49](#).

You can cite `qnetworks` in a technical paper as:

Moreno Marzolla, *The qnetworks Toolbox: A Software Package for Queueing Networks Analysis*. Khalid Al-Begain, Dieter Fiems and William J. Knottenbelt, Editors, Proceedings Analytical and Stochastic Modeling Techniques and

Applications, 17th International Conference, ASMTA 2010, Cardiff, UK, June 14-16, 2010, volume 6148 of Lecture Notes in Computer Science, Springer pp. 102-116, ISBN 978-3-642-13567-5

An early draft of the above paper is also available as Technical Report [UBLCS-2010-04](#), Department of Computer Science, University of Bologna, Italy, February 2010.

If you use BibTeX, this is the citation block:

```
@inproceedings{qnetworks,
  author      = {Moreno Marzolla},
  title       = {The qnetworks Toolbox: A Software Package for Queuing
                Networks Analysis},
  booktitle   = {Analytical and Stochastic Modeling Techniques and
                Applications, 17th International Conference,
                ASMTA 2010, Cardiff, UK, June 14-16, 2010. Proceedings},
  editor      = {Khalid Al-Begain and
                Dieter Fiems and
                William J. Knottenbelt},
  year        = {2010},
  publisher   = {Springer},
  series      = {Lecture Notes in Computer Science},
  volume      = {6148},
  pages       = {102--116},
  ee          = {http://dx.doi.org/10.1007/978-3-642-13568-2_8},
  isbn       = {978-3-642-13567-5}
}
```

2 Installing the `qnetworks` package

The most recent version of the `qnetworks` package can be downloaded from

<http://www.moreno.marzolla.name/software/qnetworks/>

Currently, the most recent version is 0.8.4, and is distributed in source form in the ‘`qnetworks-0.8.4.tar.gz`’ archive. Download the source tarball from the URL above, unpack it somewhere:

```
tar xfz qnetworks-0.8.4.tar.gz
cd qnetworks-0.8.4/
```

The `qnetworks` source distribution includes the following subdirectories:

- ‘`doc/`’ Documentation source code
- ‘`inst/`’ This directory contains the actual `m`-files which implement the various Queueing Network algorithms. Note that, as a notational convention, most of the source files (and the functions defined therein) start with the ‘`qn`’ prefix.
- ‘`test/`’ This directory contains the automated test function, which is the one used by GNU Octave.
- ‘`scripts/`’ This directory contains some utility scripts taken from GNU Octave, which extract the documentation from the specially-formatted comments in the `m`-files.
- ‘`examples/`’ This directory contains examples which are automatically extracted from the ‘`demo`’ blocks in the source code. Some of these examples are included into the documentation.
- ‘`broken/`’ This directory contains scripts which are not working properly, or need additional testing before they can be included in the ‘`inst/`’ directory.

The `qnetworks` package ships with a Makefile which can be used to automatically produce the documentation (in PDF and HTML format), and automatically run all function tests. The following targets are defined:

- `all` Running ‘`make`’ (or ‘`make all`’) on the top-level `qnetworks` directory will build the necessary scripts used to extract the documentation from the comments embedded in the `m`-files. Then, it will produce the ‘`doc/qnetworks.pdf`’ and ‘`doc/qnetworks.html`’ files which contain the documentation in PDF and HTML format, respectively.
- `check` Running ‘`make check`’ will execute all the test functions contained in the `m`-files. If you modify the code of any function from the ‘`inst/`’ directory, please run the test to ensure that no errors are introduced. Furthermore, you are encouraged to contribute new test functions to `qnetworks`, to help verifying that the algorithms are implemented correctly.

clean

distclean

dist The ‘make clean’, ‘make distclean’ and ‘make dist’ commands are used to clean up the source directory and prepare the distribution archive in compressed tar format.

If you want to define a new function, simply create the corresponding `m`-file in the ‘`inst/`’ directory. Each file should have the exact name of the function it defines. You should also add test blocks to ensure that your function computes the correct value; test blocks are extremely useful to help spot errors when a function is modified.

To install the `qnetworks` package, you can copy all `.m` files from the ‘`inst/`’ directory to a location where Octave can find them. You can also start Octave with the ‘`-p`’ option to tell it to add a path to its search path, so that it will find the functions automatically without the need to move them:

```
octave -p /path/to/qnetworks
```

For example, if all `qnetworks` `m`-files are installed in ‘`/usr/local/qnetworks`’, then you can start Octave as follows:

```
octave -p '/usr/local/qnetworks'
```

Alternatively, you can use the ‘`pkg install`’ Octave command to install the tarball directly. Start GNU Octave, and type the following command at the prompt:

```
octave:1> pkg install qnetworks-0.8.4.tar.gz
```

In this way, the `qnetworks` package can be uninstalled at any time with the ‘`pkg uninstall qnetworks`’ Octave command.

You should now be able to use all `qnetworks` functions by simply invoking their name. You can also get on-line help about each function using the `help` Octave command. For example:

```
octave:2> help qnmvablo
```

will print the documentation for the `qnmvablo` function. Additional information can be found in the `qnetworks` manual, which is available in PDF format in ‘`doc/qnetworks.pdf`’ and in HTML format in ‘`doc/qnetworks.html`’.

Within GNU Octave, you can also run the tests and demo blocks associated to the various functions, using the `test` and `demo` commands. For example, to run all the tests blocks of the `qnmvablo` function, use the following:

```
octave:3> test qnmvablo
+ PASSES 4 out of 4 tests
```

To execute the demo blocks of the `qnclosed` function, use the following:

```
octave:4> demo qnclosed
```

3 Getting Started

In this chapter we illustrate some usage examples of the `qnetworks` package. Additional examples are embedded in some of the function files; to display and execute the demos associated with function `fname` you can type `demo("fname")` at the Octave prompt. For example

```
demo("qnclosed");
```

executes all demos (if any) for the `qnclosed` function.

3.1 Analysis of Closed Networks

Let us consider a simple closed network with $K = 3$ service centers. Each center is of type $M/M/1$ -FCFS. We denote with S_i the average service time at center i , $i = 1, 2, 3$. Let $S_1 = 1.0$, $S_2 = 2.0$ and $S_3 = 0.8$. The routing probability matrix is defined as follows:

$$P = \begin{pmatrix} 0 & 0.3 & 0.7 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

This network can be analyzed with the `qnclosed` function; in the case of single-class closed networks, as in the example above, the `qnclosed` function is a front-end to `qnclosedsinglemva` which implements the Mean Value Analysis (MVA) algorithm for single-class Queueing Networks.

`qnclosed` requires the following parameters:

- N Number of requests in the network
- S Array of average service times at the centers: $S(k)$ is the average service time at center k .
- V Array of visit ratios: $V(k)$ is the average number of visits to center k .

The visit count V_k to center k can be computed with the `qnvisits` function:

```
P = [0 0.3 0.7; 1 0 0; 1 0 0];
V = qnvisits(P)
⇒ V = 1.00000 0.30000 0.70000
```

Note that the visit counts V_k satisfy the following relation:

$$V_j = \sum_{i=1}^K V_i P_{ij}$$

We can check that the computed values satisfy the above equation by evaluating the following expression:

```
V*P
⇒ ans = 1.00000 0.30000 0.70000
```

Now, we can analyze the network for a given population size N (for example, $N = 10$) as follows:

```

N = 10;
S = [1 2 0.8];
V = [1 0.3 0.7];
[U R Q X] = qnclosed( N, S, V )
⇒ U = 0.99139 0.59483 0.55518
⇒ R = 7.4360 4.7531 1.7500
⇒ Q = 7.3719 1.4136 1.2144
⇒ X = 0.99139 0.29742 0.69397

```

The output of the `qnclosed` function includes the center k utilization U_k , response time R_k , average number of customers Q_k and throughput X_k . In this particular case, for example, the throughput of center 1 is $X_1 = 0.99139$, and the average number of requests in center 3 is $Q_3 = 1.2144$. The utilization of center 1 is $U_1 = 0.99139$: note that center 1 has the higher utilization among the service centers, so it is the *bottleneck device*.

You can also use the `qnsolve` function to analyze this network. `qnsolve` can be applied to open, closed or mixed networks, and allows the network to be described in a very flexible way.

First, we let $Q1$, $Q2$ and $Q3$ to be the variables describing the service centers. Each variable is instantiated with the `qnmknode` function.

```

Q1 = qnmknode( "m/m/m-fcfs", 1 );
Q2 = qnmknode( "m/m/m-fcfs", 2 );
Q3 = qnmknode( "m/m/m-fcfs", 0.8 );

```

The first parameter of `qnmknode` is a string describing the type of the node. Here we use "m/m/m-fcfs" to denote a $M/M/m$ -FCFS center. The second parameter gives the average service time. An optional third parameter can be used to specify the number m of service centers. If omitted, it is assumed $m = 1$ (single-server node).

Now, the network can be analyzed as follows:

```

N = 10;
V = [1 0.3 0.7];
[U R Q X] = qnsolve( "closed", N, { Q1, Q2, Q3 }, V )
⇒ U = 0.99139 0.59483 0.55518
⇒ R = 7.4360 4.7531 1.7500
⇒ Q = 7.3719 1.4136 1.2144
⇒ X = 0.99139 0.29742 0.69397

```

Of course, we get exactly the same results. Other functions can be used for closed networks, see [Section 6.3 \[Algorithms for Product-Form QN\]](#), page 28.

3.2 Analysis of Open Networks

Open networks can be analyzed in a similar way. Let us consider an open network with $K = 3$ service centers, and routing probability matrix as follows:

$$P = \begin{pmatrix} 0 & 0.3 & 0.5 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

Note that in this network, requests can leave the system with probability $(1 - 0.3 - 0.5 = 0.2)$ after completing service at center 1. Let us consider external arrivals to center 1 with rate $\lambda_1 = 0.15$; arrival rates to center 2 and 3 are zero.

Similarly with closed networks, we first need to compute the visit counts V_k to center k . This can be done with the `qnvisits` function as follows:

```
P = [0 0.3 0.5; 1 0 0; 1 0 0];
lambda = [0.15 0 0];
V = qnvisits(P, lambda)
⇒ V = 5.00000 1.50000 2.50000
```

The visit counts V_k open networks satisfy the following equation:

$$V_j = P_{0j} + \sum_{i=1}^K V_i P_{ij}$$

where P_{0j} is the probability of an external arrival to center j . This can be computed as:

$$P_{0j} = \frac{\lambda_j}{\sum_{i=1}^K \lambda_i}$$

Assuming the same service times as in the previous example, the network can be analyzed with the `qnopen` function, as follows:

```
S = [1 2 0.8];
[U R Q X] = qnopen( sum(lambda), S, V )
⇒ U = 0.75000 0.45000 0.30000
⇒ R = 4.0000 3.6364 1.1429
⇒ Q = 3.00000 0.81818 0.42857
⇒ X = 0.75000 0.22500 0.37500
```

Note that the first parameter of the `qnopen` function is the (scalar) aggregate arrival rate.

Again, it is possible to use the `qnsolve` high-level function:

```
Q1 = qnmknode( "m/m/m-fcfs", 1 );
Q2 = qnmknode( "m/m/m-fcfs", 2 );
Q3 = qnmknode( "m/m/m-fcfs", 0.8 );
lambda = [0.15 0 0];
[U R Q X] = qnsolve( "open", sum(lambda), { Q1, Q2, Q3 }, V )
⇒ U = 0.75000 0.45000 0.30000
⇒ R = 4.0000 3.6364 1.1429
⇒ Q = 3.00000 0.81818 0.42857
⇒ X = 0.75000 0.22500 0.37500
```

3.3 Markov Chains Analysis

(TBD)

4 Markov Chains

4.1 Discrete-Time Markov Chains

`p = dtmc_solve (P)` [Function File]

Compute the steady-state probability vector $p(1), p(2), \dots, p(N)$ for a Discrete-Time Markov Chain with $N \times N$ transition probability matrix P .

INPUTS

P $P(i, j)$ is the transition probability from state i to state j . P must be an irreducible stochastic matrix, which means that the sum of each row must be 1, and the rank of P must be equal to its dimension.

OUTPUTS

p $p(i)$ is the steady-state probability that the system is in state i . p satisfies the equations $p = pP$ and $\sum_i p_i = 1$

4.2 Continuous-Time Markov Chains

`q = ctmc_solve (Q)` [Function File]

Compute the steady-state probability vector $q = [q(1), q(2), \dots, q(N)]$ for a Continuous-Time Markov Chain with $N \times N$ infinitesimal generator matrix Q . The steady state probability vector q satisfies the equation $qQ = 0$ and $\sum_i q_i = 1$.

If the i -th column of matrix Q is zero, then we will set $q(i) = 0$, for any i .

INPUTS

Q Infinitesimal generator matrix. $Q(i, j)$ is the transition rate from state i to state j , for $i \neq j$. The matrix Q must also satisfy the condition $\text{sum}(Q, 2) == 0$

OUTPUTS

q $q(i)$ is the steady-state probability that the system is in state i .

EXAMPLE

Consider a two-state CTMC such that transition rates between states are equal to 1. This can be solved as follows:

```
Q = [ -1  1; \
      1 -1 ];
q = ctmc_solve(Q)
⇒ q = 0.50000  0.50000
```

4.2.1 Birth-Death process

`p = ctmc_bd_solve (birth, death)` [Function File]

Compute the steady-state solution of a birth-death process with state space $(1, \dots, N)$.

INPUTS

birth *birth* is a vector with $N - 1$ elements, where $\mathit{birth}(i)$ denotes the transition rate from state i to state $i + 1$.

death *death* is a vector with $N - 1$ elements, where $\mathit{death}(i)$ denotes the transition rate from state $i + 1$ to state i

OUTPUTS

p $p(i)$ is the steady-state probability that the system is in state i . p is a vector with N elements.

4.2.2 Expected Sojourn Time

Given a N state continuous-time Markov Chain with infinitesimal generator matrix \mathbf{Q} , we define the vector $\mathbf{L}(t) = (L_1(t), L_2(t), \dots, L_N(t))$ such that $L_i(t)$ is the expected sojourn time in state i during the interval $[0, t)$, assuming that the initial occupancy probability at time 0 was $\pi(0)$. Then, $\mathbf{L}(t)$ is the solution of the following differential equation:

$$\frac{d\mathbf{L}(t)}{dt} = \mathbf{L}(t)\mathbf{Q} + \pi(0), \quad \mathbf{L}(0) = \mathbf{0}$$

The function `ctmc_exps` can be used to compute $\mathbf{L}(t)$, by using the `lsode` Octave function to solve the above linear differential equation.

$L = \mathit{ctmc_exps}(Q, tt, p)$ [Function File]
 Compute the *expected total time* $L(t, j)$ spent in state j during the time interval $[0, tt(t))$, assuming that at time 0 the state occupancy probability was p .

INPUTS

Q Infinitesimal generator matrix. $Q(i, j)$ is the transition rate from state i to state j , for $i \neq j$, $1 \leq i, j \leq N$. The matrix Q must also satisfy the condition `sum(Q, 2) == 0`

tt This parameter is a vector used for numerical integration. The first element $tt(1)$ must be 0, and the last element $tt(\mathit{end})$ must be the upper limit of the interval $[0, t)$ of interest (`tt(end) == t`).

p $p(i)$ is the probability that at time 0 the system was in state i , for all $i = 1, 2, \dots, N$

OUTPUTS

L $L(t, j)$ is the expected time spent in state j during the interval $[0, tt(t))$. $1 \leq t \leq \mathit{length}(tt)$

EXAMPLE

Let us consider a pure-birth, 4-states CTMC such that the transition rate from state i to state $i + 1$ is $\lambda_i = i\lambda$ ($i = 1, 2, 3$), with $\lambda = 0.5$. The following code computes the expected sojourn time in state i , $i = 1, 2, 3$ given initial occupancy probability $p_0 = (1, 0, 0, 0)$.

```

lambda = 0.5;
N = 4;
birth = lambda*linspace(N-1,1,N-1);
death = zeros(1,N-1);
Q = diag(birth,1)+diag(death,-1);
Q -= diag(sum(Q,2));
tt = linspace(0,10,100);
p0 = zeros(1,N); p0(1)=1;
L = ctmc_exps(Q,tt,p0);
plot( tt, L(:,1), ";State 1;", "linewidth", 2, \
      tt, L(:,2), ";State 2;", "linewidth", 2, \
      tt, L(:,3), ";State 3;", "linewidth", 2, \
      tt, L(:,4), ";State 4 (absorbing);", "linewidth", 2);
legend("location","northwest");
xlabel("Time");
ylabel("Expected sojourn time");

```

4.2.3 Time-Averaged Expected Sojourn Time

$M = \text{ctmc_taexps}(Q, tt, p)$ [Function File]

Compute the *time-averaged sojourn time* $M(t, j)$, defined as the fraction of the time interval $[0, tt(t))$ spent in state j , assuming that at time 0 the state occupancy probability was p .

INPUTS

- Q Infinitesimal generator matrix. $Q(i, j)$ is the transition rate from state i to state j , for $i \neq j$, $1 \leq i, j \leq N$. The matrix Q must also satisfy the condition $\text{sum}(Q, 2) == 0$
- tt This parameter is a vector used for numerical integration of the sojourn time. The first element $tt(1)$ must be 0, and the last element $tt(\text{end})$ must be the upper limit of the interval $[0, t)$ of interest ($tt(\text{end}) == t$). This vector is used by the ODE solver to compute the solution M .
- p $p(i)$ is the probability that, at time 0, the system was in state i , for all $i = 1, 2, \dots, N$

OUTPUTS

- M $M(t, j)$ is the expected fraction of time spent in state j during the interval $[0, tt(t))$ assuming that the state occupancy probability at time zero was p . $1 \leq t \leq \text{length}(tt)$

EXAMPLE

```

lambda = 0.5;
N = 4;
birth = lambda*linspace(N-1,1,N-1);
death = zeros(1,N-1);
Q = diag(birth,1)+diag(death,-1);
Q -= diag(sum(Q,2));
t = linspace(0.001,10,100);
p = zeros(1,N); p(1)=1;
M = ctmc_taeyps(Q,t,p);
plot(t, M(:,1), ";State 1;", "linewidth", 2, \
      t, M(:,2), ";State 2;", "linewidth", 2, \
      t, M(:,3), ";State 3;", "linewidth", 2);
legend("location","northeast");
xlabel("Time");
ylabel("Time-averaged Expected sojourn time");

```

4.2.4 Expected Time to Absorption

If we have a Markov Chain with absorbing states, it is possible to define the *expected time to absorption* as the expected time until the system goes into an absorbing state. More specifically, let us suppose that A is the set of transient (i.e., non-absorbing) states the the CTMC with N states and infinitesimal generator matrix \mathbf{Q} . Then, we define $\mathbf{L}_A(\infty)$ as the expected time to absorption as the solution of the following equation:

$$\mathbf{L}_A(\infty)\mathbf{Q}_A = -\pi_A(0)$$

where \mathbf{Q}_A is the restriction of matrix \mathbf{Q} to only states in A , and $\pi_A(0)$ is the initial state occupancy probability at time 0, also restricted only to states in A .

$t = \text{ctmc_mtta}(Q, p)$ [Function File]

Compute the Mean-Time to Absorption (MTTA) starting from initial occupancy probability p at time 0. If there are no absorbing states, this function fails with an error.

INPUTS

Q $N \times N$ infinitesimal generator matrix. $Q(i, j)$ is the transition rate from state i to state j , $i \neq j$. The matrix Q must satisfy the condition $\text{sum}(Q, 2) == 0$

p $p(i)$ is the probability that the system is in state i at time 0, for each $i = 1, 2, \dots, N$

OUTPUTS

t Mean time to absorption of the process represented by matrix Q . If there are no absorbing states, this function fails.

EXAMPLE

Let us consider a simple model of a redundant disk array. We assume that the array is made of 5 independent disks, such that the array can tolerate up to 2 disk failures. If

three or more disks break, the array is dead and unrecoverable. We want to estimate the Mean-Time-To-Failure (MTTF) of the disk array.

We model this system as a 4 states Markov chain with state space $\{2, 3, 4, 5\}$ such that state i denotes that exactly i disks are active. State 2 is absorbing. Let λ denotes the failure rate of a single disk. The system starts in state 5 (all disks are operational). This is a pure death process, where the death rate from state i to state $i - 1$ (for all $i > 2$) is λi .

It turns out that the MTTF in this case is the MTTA. We can compute the MTTF (MTTA) as follows:

```
lambda = 0.01;
death = [ 3*lambda 4*lambda 5*lambda ];
Q = diag(death,-1);
Q -= diag(sum(Q,2));
t = ctmc_mttt(Q,[0 0 0 1])
```

REFERENCES

G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998.

5 Single Station Queueing Systems

Single Station Queueing Systems, as the name suggests, are special queueing systems which are made by a single station. Thus, such systems are quite easy to analyze. The `qnetworks` package contains functions for handling the following kind of systems:

- $M/M/1$ single-server queueing station;
- $M/M/m$ multiple-server queueing station;
- $M/M/\infty$ infinite-server station (delay center);
- $M/M/1/K$ single-server, finite-capacity queueing station;
- $M/M/m/K$ multiple-server, finite-capacity queueing station;
- $M/G/1$ system;
- $M/H_m/1$ system.

Note that these functions can be used as building blocks for analyzing Queueing Networks. For example, Jackson networks can be analyzed by computing the aggregate arrival rates to each node, and then solving each node in isolation as if it were a single station queueing system.

5.1 The $M/M/1$ System

The $M/M/1$ system is made of a single server connected to an unlimited FCFS queue. The mean arrival rate is Poisson with arrival rate λ , while the service time is exponentially distributed with average service rate μ . The system is stable if $\lambda < \mu$.

`[U, R, Q, X, p0] = qnmm1 (lambda, mu)` [Function File]

Compute utilization, response time, average number of requests and throughput for a $M/M/1$ queue.

The steady-state probability π_k that there are k jobs in the system, $k \geq 0$, can be computed as:

$$\pi_k = (1 - \rho)\rho^k$$

where $\rho = \lambda/\mu$ is the server utilization.

INPUTS

`lambda` Arrival rate (jobs/s, `lambda > 0`).

`mu` Service rate (jobs/s, `mu > lambda`).

OUTPUTS

`U` Server utilization

`R` Service center response time

`Q` Average number of requests in the system

`X` Service center throughput. If the system is ergodic, we will always have `X = lambda`

`p0` Steady-state probability that there are no requests in the system.

$lambda$ and mu can be vectors of the same size. In this case, the results will be vectors as well.

See also: qnmmm, qnmminf, qnmnmk.

REFERENCES

G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998, Section 6.3.

5.2 The $M/M/m$ System

The $M/M/m$ system is similar to the $M/M/1$ system, except that there are $m \geq 1$ servers connected to a single queue. Thus, at most m requests can be in service at the same time. The $M/M/m$ system can be seen as a single server with load-dependent service time $\mu(n)$, which is a function of the number n of nodes in the center:

$$\mu(n) = \min(m, n) * \mu$$

$[U, R, Q, X, p0, pm] = \text{qnmmm}(lambda, mu)$ [Function File]

$[U, R, Q, X, p0, pm] = \text{qnmmm}(lambda, mu, m)$ [Function File]

Compute utilization, response time, average number of requests in service and throughput for a $M/M/m$ queue, a queueing system with m service centers connected to a single queue.

The steady-state probability π_k that there are k jobs in the system, $k \geq 0$, can be computed as:

$$\pi_k = \begin{cases} \pi_0 \frac{(m\rho)^k}{k!} & 0 \leq k \leq m; \\ \pi_0 \frac{\rho^k m^m}{m!} & k > m. \end{cases}$$

where $\rho = \lambda/(m\mu)$ is the individual server utilization. The steady-state probability π_0 that there are no jobs in the system can be computed as:

$$\pi_0 = \left[\sum_{k=0}^{m-1} \frac{(m\rho)^k}{k!} + \frac{(m\rho)^m}{m!} \frac{1}{1-\rho} \right]^{-1}$$

INPUTS

$lambda$ Arrival rate (jobs/s, $lambda > 0$).

mu Service rate (jobs/s, $mu > lambda$).

m Number of servers ($m > 0$). If omitted, it is assumed $m=1$.

OUTPUTS

U Service center utilization, $U = \lambda/(m\mu)$.

R Service center response time

Q Average number of requests in the system

X Service center throughput. If the system is ergodic, we will always have $X = \mathit{lambda}$

$p0$ Steady-state probability that there are 0 requests in the system

pm Steady-state probability that an arriving request has to wait in the queue

lambda , μ and m can be vectors of the same size. In this case, the results will be vectors as well.

See also: `qnmml`, `qnmminf`, `qnmmlmk`.

REFERENCES

G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998, Section 6.5.

5.3 The $M/M/\infty$ System

The $M/M/\infty$ system is similar to the $M/M/m$ system, except that there are infinitely many servers (that is, $m = \infty$). Thus, there is no queueing at this node, as each arriving job always finds a free server. The $M/M/\infty$ system is always stable, regardless what the arrival and service rates λ and μ are.

`[U, R, Q, X, p0] = qnmminf (lambda, mu)` [Function File]

Compute utilization, response time, average number of requests and throughput for a $M/M/\infty$ queue. This is a system with an infinite number of servers. Note that a $M/M/\infty$ system is always stable, regardless the values of the arrival and service rates.

The steady-state probability π_k that there are k requests in the system, $k \geq 0$, can be computed as:

$$\pi_k = \frac{1}{k!} \left(\frac{\lambda}{\mu} \right)^k e^{-\lambda/\mu}$$

INPUTS

lambda Arrival rate (jobs/s, $\mathit{lambda} > 0$).

μ Service rate (jobs/s, $\mu > 0$).

OUTPUTS

U Traffic intensity (defined as λ/μ). Note that this is different from the utilization, which in the case of $M/M/\infty$ centers is always zero.

R Service center response time.

Q Average number of requests in the system (which is equal to the traffic intensity λ/μ).

X Throughput (which is always equal to $X = \mathit{lambda}$).

$p0$ Steady-state probability that there are no requests in the system

λ and μ can be vectors of the same size. In this case, the results will be vectors as well.

See also: qnmm1,qnmmm,qnmmmk.

REFERENCES

G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998, Section 6.4.

5.4 The $M/M/1/K$ System

In a $M/M/1/K$ finite capacity system there can be at most k jobs at any time. If a new request tries to join the system when there are already K other requests, the arriving request is lost. The queue has $K - 1$ slots. The $M/M/1/K$ system is always stable, regardless of the arrival and service rates λ and μ .

$[U, R, Q, X, p0, pK] = \text{qnmm1k}(\lambda, \mu, K)$ [Function File]

Compute utilization, response time, average number of requests and throughput for a $M/M/1/K$ finite capacity system. In a $M/M/1/K$ queue there is a single server, the maximum number of requests is K , and the maximum queue length is $K - 1$.

The steady-state probability π_k that there are k jobs in the system, $0 \leq k \leq K$, can be computed as:

$$\pi_k = \frac{(1 - a)a^k}{1 - a^{K+1}}$$

where $a = \lambda/\mu$.

INPUTS

λ Arrival rate (jobs/s, $\lambda > 0$).

μ Service rate (jobs/s, $\mu > 0$).

K Maximum number of requests allowed in the system ($K \geq 1$).

OUTPUTS

U Service center utilization, which is defined as $U = 1 - p0$

R Service center response time

Q Average number of requests in the system

X Service center throughput

$p0$ Steady-state probability that there are no requests in the system

pK Steady-state probability that there are K requests in the system (i.e., that the system is full)

λ , μ and K can be vectors of the same size. In this case, the results will be vectors as well.

See also: qnmm1,qnmminf,qnmmm.

5.5 The $M/M/m/K$ System

The $M/M/m/K$ finite capacity system is similar to the $M/M/1/k$ system except that the number of servers is m , where $1 \leq m \leq K$. The queue is made of $K - m$ slots. The $M/M/m/K$ system is always stable.

$[U, R, Q, X, p0, pK] = \text{qnmnmk}(\text{lambda}, \text{mu}, m, K)$ [Function File]

Compute utilization, response time, average number of requests and throughput for a $M/M/m/K$ finite capacity system. In a $M/M/m/K$ queue there are $m \geq 1$ service centers. At any time, at most $K \geq m$ requests can be in the system. This function generates and solves the underlying CTMC.

The steady-state probability π_k that there are k jobs in the system, $0 \leq k \leq K$ can be expressed as:

$$\pi_k = \begin{cases} \frac{\rho^k}{k!} \pi_0 & \text{if } 0 \leq k \leq m; \\ \frac{\rho^m}{m!} \left(\frac{\rho}{m}\right)^{k-m} \pi_0 & \text{if } m < k \leq K \end{cases}$$

where $\rho = \lambda/\mu$ is the offered load. The probability π_0 that the system is empty can be computed by considering that all probabilities must sum to one: $\sum_{k=0}^K \pi_k = 1$, which gives:

$$\pi_0 = \left[\sum_{k=0}^m \frac{\rho^k}{k!} + \frac{\rho^m}{m!} \sum_{k=m+1}^K \left(\frac{\rho}{m}\right)^{k-m} \right]^{-1}$$

INPUTS

- lambda* Arrival rate ($\text{lambda} > 0$).
- mu* Service rate ($\text{mu} > 0$).
- m* Number of servers ($m \geq 1$).
- K* Maximum number of requests allowed in the system, including those inside the service centers ($K \geq m$).

OUTPUTS

- U* Service center utilization
- R* Service center response time
- Q* Average number of requests in the system
- X* Service center throughput
- p0* Steady-state probability that there are no requests in the system.
- pK* Steady-state probability that there are K requests in the system (i.e., probability that the system is full).

lambda, *mu*, *m* and *K* can be either scalars, or vectors of the same size. In this case, the results will be vectors as well.

See also: qnmm1, qnmminf, qnmnm.

REFERENCES

G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998, Section 6.6.

5.6 The Asymmetric $M/M/m$ System

The Asymmetric $M/M/m$ system contains m servers connected to a single queue. Differently from the $M/M/m$ system, in the asymmetric $M/M/m$ each server may have a different service time.

`[U, R, Q, X] = qnammm (lambda, mu)` [Function File]

Compute *approximate* utilization, response time, average number of requests in service and throughput for an asymmetric $M/M/m$ queue. In this system there are m different service centers connected to a single queue. Each server has its own (possibly different) service time. If there is more than one server available, the requests are directed to a randomly-chosen one.

INPUTS

`lambda` Arrival rate (jobs/s, $lambda > 0$).

`mu` $mu(i)$ is the service rate (jobs/s) of server i , $1 \leq i \leq m$. The system must be ergodic ($lambda < sum(mu)$).

OUTPUTS

`U` Approximate service center utilization, $U = \lambda / (\sum_i \mu_i)$.

`R` Approximate service center response time

`Q` Approximate number of requests in the system

`X` Approximate service center throughput. If the system is ergodic, we will always have $X = lambda$

See also: qnammm.

REFERENCES

G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998

5.7 The $M/G/1$ System

`[U, R, Q, X, p0] = qnmg1 (lambda, xavg, x2nd)` [Function File]

Compute utilization, response time, average number of requests and throughput for a $M/G/1$ system. The service time distribution is described by its mean `xavg`, and by its second moment `x2nd`. The computations are based on results from L. Kleinrock, *Queueing Systems*, Wiley, Vol 2, and Pollaczek-Khinchine formula.

INPUTS

`lambda` Arrival rate.

`xavg` Average service time

x2nd Second moment of service time distribution

OUTPUTS

U Service center utilization

R Service center response time

Q Average number of requests in the system

X Service center throughput

p0 probability that there is not any request at system

lambda, *xavg*, *t2nd* can be vectors of the same size. In this case, the results will be vectors as well.

See also: `qnmh1`.

5.8 The $M/H_m/1$ System

`[U, R, Q, X, p0] = qnmh1 (lambda, mu, alpha)` [Function File]

Compute utilization, response time, average number of requests and throughput for a $M/H_m/1$ system. In this system, the customer service times have hyper-exponential distribution:

$$B(x) = \sum_{j=1}^m \alpha_j (1 - e^{-\mu_j x}), \quad x > 0$$

where α_j is the probability that the request is served at phase j , in which case the average service rate is μ_j . After completing service at phase j , for some j , the request exits the system.

INPUTS

lambda Arrival rate.

mu `mu(j)` is the phase j service rate. The total number of phases m is `length(mu)`.

alpha `alpha(j)` is the probability that a request is served at phase j . *alpha* must have the same size as *mu*.

OUTPUTS

U Service center utilization

R Service center response time

Q Average number of requests in the system

X Service center throughput

6 Queueing Networks

6.1 Introduction

Queueing Networks (QN) are a very simple yet powerful modeling tool which is used to analyze many kind of systems. In its simplest form, a QN is made of K service centers. Each service center i has a queue, which is connected to m_i (generally identical) *servers*. Customers (or requests) arrive at the service center, and join the queue if there is a slot available. Then, requests are served according to a (de)queueing policy. After service completes, the requests leave the service center.

The service centers for which $m_i = \infty$ are called *delay centers* or *infinite servers*. If a service center has infinite servers, of course each new request will find one server available, so there will never be queueing.

Requests join the queue according to a *queueing policy*, such as:

FCFS First-Come-First-Served

LCFS-PR Last-Come-First-Served, Preemptive Resume

PS Processor Sharing

IS Infinite Server, there is an infinite number of identical servers so that each request always finds a server available, and there is no queueing

A population of *requests* or *customers* arrives to the system system, requesting service to the service centers. The request population may be *open* or *closed*. In open systems there is an infinite population of requests. New customers arrive from outside the system, and eventually leave the system. In closed systems there is a fixed population of request which continuously interacts with the system.

There might be a single class of requests, meaning that all requests behave in the same way (e.g., they spend the same average time on each particular server), or there might be multiple classes of requests.

6.1.1 Single class models

In single class models, all requests are indistinguishable and belong to the same class. This means that every request has the same average service time, and all requests move through the system with the same routing probabilities.

Model Inputs

λ_i External arrival rate to service center i .

λ Overall external arrival rate to the whole system: $\lambda = \sum_i \lambda_i$.

S_i Average service time. S_i is the average service time on service center i . In other words, S_i is the average time from the instant in which a request is extracted from the queue and starts being service, and the instant at which service finishes and the request moves to another queue (or exits the system).

P_{ij} Routing probability matrix. $\mathbf{P} = P_{ij}$ is a $K \times K$ matrix such that P_{ij} is the probability that a request completing service at server i will move directly to server j , The probability that a request leaves the system after service at service center i is $1 - \sum_{j=1}^K P_{ij}$.

V_i Average number of visits. V_i is the average number of visits to the service center i . This quantity will be described shortly.

Model Outputs

U_i Service center utilization. U_i is the utilization of service center i . The utilization is defined as the fraction of time in which the resource is busy (i.e., the server is processing requests).

R_i Average response time. R_i is the average response time of service center i . The average response time is defined as the average time between the arrival of a customer in the queue, and the completion of service.

Q_i Average number of customers. Q_i is the average number of requests in service center i . This includes both the requests in the queue, and the request being served.

X_i Throughput. X_i is the throughput of service center i . The throughput is defined as the ratio of job completions (i.e., average number of jobs completed over a fixed interval of time).

Given these output parameters, additional performance measures can be computed as follows:

X System throughput, $X = X_1/V_1$

R System response time, $R = \sum_{k=1}^K R_k V_k$

Q Average number of requests in the system, $Q = N - XZ$

For open, single-class models, the scalar λ denotes the external arrival rate of requests to the system. The average number of visits satisfy the following equation:

$$V_j = P_{0j} + \sum_{i=1}^K V_i P_{ij}$$

where P_{0j} is the probability that an external arrival goes to service center j . If λ_j is the external arrival rate to service center j , and $\lambda = \sum_j \lambda_j$ is the overall external arrival rate, then $P_{0j} = \lambda_j/\lambda$.

For closed models, the scalar N denotes the population size, i.e., the number of requests in the system. For closed networks, the visit ratios satisfy the following equation:

$$V_j = \sum_{i=1}^K V_i P_{ij}, \quad V_1 = 1$$

6.1.2 Multiple class models

In multiple class QN models, we assume that there exist C different classes of requests. Each request from class c spends on average time S_{ck} in service at service center k . For open models, we denote with $\lambda = \lambda_{ck}$ the arrival rates, where λ_{ck} is the external arrival rate of class c customers at service center k . For closed models, we denote with $\mathbf{N} = (N_1, N_2, \dots, N_C)$ the population vector, where N_c is the number of class c requests in the system.

The transition probability matrix for these kind of networks will be a $C \times K \times C \times K$ matrix $\mathbf{P} = P_{risj}$ such that P_{risj} is the probability that a class r request which completes service at center i will join server j as a class s request.

Model input and outputs can be adjusted by adding additional indexes for the customer classes.

Model Inputs

λ_{ci}	External arrival rate of class- c requests to service center i
λ	Overall external arrival rate to the whole system: $\lambda = \sum_c \sum_i \lambda_{ci}$
S_{ci}	Average service time. S_{ci} is the average service time on service center i for class c requests.
P_{risj}	Routing probability matrix. $\mathbf{P} = P_{risj}$ is a $C \times K \times C \times K$ matrix such that P_{risj} is the probability that a class r request which completes service at server i will move to server j as a class s request.
V_{ci}	Average number of visits. V_{ci} is the average number of visits of class c requests to the service center i .

Model Outputs

U_{ci}	Utilization of service center i by class c requests. The utilization is defined as the fraction of time in which the resource is busy (i.e., the server is processing requests).
R_{ci}	Average response time experienced by class c requests on service center i . The average response time is defined as the average time between the arrival of a customer in the queue, and the completion of service.
Q_{ci}	Average number of class c requests on service center i . This includes both the requests in the queue, and the request being served.
X_{ci}	Throughput of service center i for class c requests. The throughput is defined as the rate of completion of class c requests.

It is possible to define aggregate performance measures as follows:

U_i	Utilization of service center i : $U_i = \sum_{c=1}^C U_{ci}$
R_c	System response time for class c requests: $R_c = \sum_{i=1}^K R_{ci} V_{ci}$
Q_c	Average number of class c requests in the system: $Q_c = \sum_{i=1}^K Q_{ci}$
X_c	Class c throughput: $X_c = X_{c1}/V_{c1}$

We can define the visit ratios V_{sj} for class s customers at service center j as follows:

$$V_{sj} = \sum_{r=1}^C \sum_{i=1}^K V_{ri} P_{risj}, \quad V_{s1} = 1$$

while for open networks:

$$V_{sj} = P_{0sj} + \sum_{r=1}^C \sum_{i=1}^K V_{ri} P_{risj}$$

where P_{0sj} is the probability that an external arrival goes to service center j as a class- s request. If λ_{sj} is the external arrival rate of class s requests to service center j , and $\lambda = \sum_s \sum_j \lambda_{sj}$ is the overall external arrival rate to the whole system, then $P_{0sj} = \lambda_{sj}/\lambda$.

6.2 Generic Queueing Network Analysis

The `qnetworks` package provides a couple of high-level functions for defining and solving QN models. These functions can be used to define a open or closed QN model (with single or multiple job classes), with arbitrary configuration and queueing disciplines. At the moment only product-form networks can be solved, See [Section 6.3 \[Algorithms for Product-Form QN\]](#), page 28.

The network is defined by two parameters. The first one is the list of nodes, encoded as an Octave *cell array*. The second parameter is the visit ration V , which can be either a vector (for single-class models) or a two-dimensional matrix (for multiple-class models).

Individual nodes in the network are structures build using the `qnmknode` function.

```

Q = qnmknode ("m/m/m-fcfs", S) [Function File]
Q = qnmknode ("m/m/m-fcfs", S, m) [Function File]
Q = qnmknode ("m/m/1-lcfs-pr", S) [Function File]
Q = qnmknode ("-/g/1-ps", S) [Function File]
Q = qnmknode ("-/g/1-ps", S, s2) [Function File]
Q = qnmknode ("-/g/inf", S) [Function File]
Q = qnmknode ("-/g/inf", S, s2) [Function File]

```

Creates a node; this function can be used together with `qnsolve`. It is possible to create either single-class nodes (where there is only one customer class), or multiple-class nodes (where the service time is given per-class). Furthermore, it is possible to specify load-dependent service times.

INPUTS

S Average service time. S can be either a scalar, a row vector, a column vector or a two-dimensional matrix.

- If S is a scalar, it is assumed to be a load-independent, class-independent service time.
- If S is a column vector, then $S(c)$ is assumed to be the load-independent service time for class c customers.
- If S is a row vector, then $S(n)$ is assumed to be the class-independent service time at the node, when there are n requests.
- Finally, if S is a two-dimensional matrix, then $S(c, n)$ is assumed to be the class c service time when there are n requests at the node.

m Number of identical servers at the node. Default is $m=1$.

$s2$ Squared coefficient of variation for the service time. Default is 1.0.

The returned struct Q should be considered opaque to the client.

See also: `qnsolve`.

After the network has been defined, it is possible to solve it using the `qnsolve` function. Note that this function is somewhat less efficient than those described in later sections, but generally easier to use.

```

[U, R, Q, X] = qnsolve ("closed", N, QQ, V) [Function File]
[U, R, Q, X] = qnsolve ("closed", N, QQ, V, Z) [Function File]
[U, R, Q, X] = qnsolve ("open", lambda, QQ, V) [Function File]
[U, R, Q, X] = qnsolve ("mixed", lambda, N, QQ, V) [Function File]

```

General evaluator of QN models. Networks can be open, closed or mixed; single as well as multiclass networks are supported.

- For **closed** networks, the following server types are supported: $M/M/m$ -FCFS, $-/G/\infty$, $-/G/1$ -LCFS-PR, $-/G/1$ -PS and load-dependent variants.

- For **open** networks, the following server types are supported: $M/M/m$ -FCFS, $-/G/\infty$ and $-/G/1$ -PS. General load-dependent nodes are *not* supported. Multiclass open networks do not support multiple server $M/M/m$ nodes, but only single server $M/M/1$ -FCFS.
- For **mixed** networks, the following server types are supported: $M/M/1$ -FCFS, $-/G/\infty$ and $-/G/1$ -PS. General load-dependent nodes are *not* supported.

INPUTS

N	Number of requests in the system for closed networks. For single-class networks, N must be a scalar. For multiclass networks, $N(c)$ is the population size of closed class c .
$lambda$	External arrival rate (scalar) for open networks. For single-class networks, $lambda$ must be a scalar. For multiclass networks, $lambda(c)$ is the class c overall arrival rate.
QQ	List of queues in the network. This must be a cell array with N elements, such that $QQ\{i\}$ is a struct produced by the <code>qnmknode</code> function.
Z	External delay ("think time") for closed networks. Default 0.

OUTPUTS

U	If i is a FCFS node, then $U(i)$ is the utilization of service center i . If i is an IS node, then $U(i)$ is the <i>traffic intensity</i> defined as $X(i)*S(i)$.
R	$R(i)$ is the average response time of service center i .
Q	$Q(i)$ is the average number of customers in service center i .
X	$X(i)$ is the throughput of service center i .

Note that for multiclass networks, the computed results are per-class utilization, response time, number of customers and throughput: $U(c,k)$, $R(c,k)$, $Q(c,k)$, $X(c,k)$,

EXAMPLE

Let us consider a closed, multiclass network with $C = 2$ classes and $K = 3$ service center. Let the population be $M = (2, 1)$ (class 1 has 2 requests, and class 2 has 1 request). The nodes are as follows:

- Node 1 is a $M/M/1$ -FCFS node, with load-dependent service times. Service times are class-independent, and are defined by the matrix $[0.2 \ 0.1 \ 0.1; 0.2 \ 0.1 \ 0.1]$. Thus, $S(1,2) = 0.2$ means that service time for class 1 customers where there are 2 requests is 0.2. Note that service times are class-independent;
- Node 2 is a $-/G/1$ -PS node, with service times $S_{12} = 0.4$ for class 1, and $S_{22} = 0.6$ for class 2 requests;
- Node 3 is a $-/G/\infty$ node (delay center), with service times $S_{13} = 1$ and $S_{23} = 2$ for class 1 and 2 respectively.

After defining the per-class visit count V such that $V(c,k)$ is the visit count of class c requests to service center k . We can define and solve the model as follows:

```

QQ = { qnmknode( "m/m/m-fcfs", [0.2 0.1 0.1; 0.2 0.1 0.1] ), \
        qnmknode( "-/g/1-ps", [0.4; 0.6] ), \
        qnmknode( "-/g/inf", [1; 2] ) };
V = [ 1 0.6 0.4; \
      1 0.3 0.7 ];
N = [ 2 1 ];
[U R Q X] = qnsolve( "closed", N, QQ, V );

```

6.3 Algorithms for Product-Form QN

Product-form queueing networks fulfill the following assumptions:

- The network can consist of open and closed job classes.
- The following queueing disciplines are allowed: FCFS, PS, LCFS-PR and IS.
- Service times for FCFS nodes must be exponentially distributed and class-independent. Service centers at PS, LCFS-PR and IS nodes can have any kind of service time distribution with a rational Laplace transform. Furthermore, for PS, LCFS-PR and IS nodes, different classes of customers can have different service times.
- The service rate of an FCFS node is only allowed to depend on the number of jobs at this node; in a PS, LCFS-PR and IS node the service rate for a particular job class can also depend on the number of jobs of that class at the node.
- In open networks two kinds of arrival processes are allowed: i) the arrival process is Poisson, with arrival rate λ which can depend on the number of jobs in the network. ii) the arrival process consists of U independent Poisson arrival streams where the U job sources are assigned to the U chains; the arrival rate can be load dependent.

6.3.1 Jackson Networks

Jackson networks satisfy the following conditions:

- There is only one job class in the network; the overall number of jobs in the system is unlimited.
- There are N service centers in the network. Each service center may have Poisson arrivals from outside the system. A job can leave the system from any node.
- Arrival rates as well as routing probabilities are independent from the number of nodes in the network.
- External arrivals and service times at the service centers are exponentially distributed, and in general can be load-dependent.
- Service discipline at each node is FCFS

We define the *joint probability vector* $\pi(k_1, k_2, \dots, k_N)$ as the steady-state probability that there are k_i requests at service center i , for all $i = 1, 2, \dots, N$. Jackson networks have the property that the joint probability is the product of the marginal probabilities π_i :

$$\pi(k_1, k_2, \dots, k_N) = \prod_{i=1}^N \pi_i(k_i)$$

where $\pi_i(k_i)$ is the steady-state probability that there are k_i requests at service center i .

$[U, R, Q, X] = \text{qnjackson}(\text{lambda}, S, P)$ [Function File]
 $[U, R, Q, X] = \text{qnjackson}(\text{lambda}, S, P, m)$ [Function File]
 $\text{pr} = \text{qnjackson}(\text{lambda}, S, P, m, k)$ [Function File]

With three or four input parameters, this function computes the steady-state occupancy probabilities for a Jackson network. With five input parameters, this function computes the steady-state probability $\text{pr}(j)$ that there are $k(j)$ requests at service center j .

This function solves a subset of Jackson networks, with the following constraints:

- External arrival rates are load-independent.
- Service center i consists either of $m(i) \geq 1$ identical servers with individual average service time $S(i)$, or of an Infinite Server (IS) node.

INPUTS

lambda $\text{lambda}(i)$ is the external arrival rate to service center i . lambda must be a vector of length N , $\text{lambda}(i) \geq 0$.
 S $S(i)$ is the average service time on service center i . S must be a vector of length N , $S(i) > 0$.
 P $P(i, j)$ is the probability that a job which completes service at service center i proceeds to service center j . P must be a matrix of size $N \times N$.
 m $m(i)$ is the number of servers at service center i . If $m(i) < 1$, service center i is an infinite-server node. Otherwise, it is a regular FCFS queueing center with $m(i)$ servers. If this parameter is omitted, default is $m(i) = 1$ for all i . If this parameter is a scalar, it will be promoted to a vector with the same size as lambda . Otherwise, m must be a vector of length N .
 k Compute the steady-state probability that there are $k(i)$ requests at service center i . k must have the same length as lambda , with $k(i) \geq 0$.

OUTPUT

U If i is a FCFS node, then $U(i)$ is the utilization of service center i . If i is an IS node, then $U(i)$ is the *traffic intensity* defined as $X(i) * S(i)$.
 R $R(i)$ is the average response time of service center i .
 Q $Q(i)$ is the average number of customers in service center i .
 X $X(i)$ is the throughput of service center i .
 pr $\text{pr}(i)$ is the steady state probability that there are $k(i)$ requests at service center i .

See also: qnopen.

REFERENCES

This implementation is based on G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998, pp. 284–287.

6.3.2 The Convolution Algorithm

According to the BCMP theorem, the state probability of a closed single class queueing network with K nodes and N requests can be expressed as:

$$\pi(k_1, k_2, \dots, k_K) = \frac{1}{G(N)} \prod_{i=1}^N F_i(k_i)$$

Here $\pi(k_1, k_2, \dots, k_K)$ is the joint probability of having k_i requests at node i , for all $i = 1, 2, \dots, K$.

The *convolution algorithms* computes the normalization constant $G = (G(0), G(1), \dots, G(N))$ for single-class, closed networks with N requests. The normalization constants are returned as the Octave vector $G = [G(1), G(2), \dots, G(N+1)]$ where $G(i+1)$ is the value of $G(i)$, as Octave uses 1-base vectors. The normalization constant can be used to compute all performance measures of interest (utilization, average response time and so on).

`qnetworks` implements the convolution algorithm, in the function `qnconvolution` and `qnconvolutionld`. The first one supports single-station nodes, multiple-station nodes and IS nodes. The second one supports networks with general load-dependent service centers.

`[U, R, Q, X, G] = qnconvolution (N, S, V)` [Function File]
`[U, R, Q, X, G] = qnconvolution (N, S, V, m)` [Function File]

This function implements the *convolution algorithm* for product-form, single-class closed queueing networks. Load-independent service centers, multiple servers ($M/M/m$ queues) and IS nodes are supported. For general load-dependent service centers, use the `qnconvolutionld` function instead.

INPUTS

N Number of requests in the system ($N > 0$).

S $S(k)$ is the average service time on center k ($S(k) \geq 0$).

V $V(k)$ is the visit count of service center k ($V(k) \geq 0$).

m $m(k)$ is the number of servers at center k . If $m(k) < 1$, center k is a delay center (IS) otherwise it is a regular $M/M/m$ queueing center with $m(k)$ identical servers. Default is $m(k) = 1$ for all k .

OUTPUT

U $U(k)$ is the utilization of center k . For IS nodes, $U(k)$ is the *traffic intensity*.

R $R(k)$ is the average response time of center k .

Q $Q(k)$ is the average number of customers at center k .

X $X(k)$ is the throughput of center k .

G Normalization constants (vector). $G(n+1)$ corresponds to the normalization constant with n requests $G(n)$, $n = 0, 1, \dots, N$ as array indexes in Octave start from 1.

See also: `qnconvolutionld`.

EXAMPLE

The normalization constant G can be used to compute the steady-state probabilities for a closed single class product-form Queueing Network with K nodes. Let $\mathbf{k}=[k_1, k_2, \dots, k_K]$ be a valid population vector. Then, the steady-state probability $p(i)$ to have $k(i)$ requests at service center i can be computed as:

$$p_i(k_i) = \frac{(V_i S_i)^{k_i}}{G(K)} (G(K - k_i) - V_i S_i G(K - k_i - 1)), \quad i = 1, 2, \dots, K$$

```

k = [1 2 0];
K = sum(k); # Total population size
S = [ 1/0.8 1/0.6 1/0.4 ];
m = [ 2 3 1 ];
V = [ 1 .667 .2 ];
[U R Q X G] = qnconvolution( K, S, V, m );
p = [0 0 0]; # initialize p
# Compute the probability to have k(i) jobs at service center i
for i=1:3
    p(i) = (V(i)*S(i))k(i) / G(K+1) * \
            (G(K-k(i)+1) - V(i)*S(i)*G(K-k(i)) );
    printf("i=%d k(i)=%d prob=%f\n", i, k(i), p(i) );
endfor
+ i=1 k(i)=1 prob=0.17975
+ i=2 k(i)=2 prob=0.48404
+ i=3 k(i)=0 prob=0.52779

```

NOTE

For a network with K service centers and population size N , this implementation of the convolution algorithm has time and space complexity $O(NK)$.

REFERENCES

Jeffrey P. Buzen, *Computational Algorithms for Closed Queueing Networks with Exponential Servers*, Communications of the ACM, volume 16, number 9, september 1973, pp. 527–531. <http://doi.acm.org/10.1145/362342.362345>

This implementation is based on G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998, pp. 313–317.

`[U, R, Q, X, G] = qnconvolutionld(N, S, V)` [Function File]

This function implements the *convolution algorithm* for product-form, single-class closed queueing networks with general load-dependent service centers.

This function computes the normalization constant $G = (G(0), G(1), \dots, G(N))$ for single-class, closed networks with load-dependent service centers using the convolution algorithm. The normalization constants are returned as vector $\mathbf{G}=[G(1), G(2), \dots, G(N+1)]$ where $G(i+1)$ is the value of $G(i)$. Furthermore, this function computes utilization, response time, average number of customers and throughput of individual servers using the normalization constants.

INPUTS

N	Number of requests in the system ($N > 0$).
S	$S(k, n)$ is the average service time at center k where there are n requests ($S(k, n) \geq 0$). S can be a matrix or a function handle. If S is a function handle, it must be possible to evaluate $S(k, n)$ when n is a vector.
V	$V(k)$ is the visit count of service center k ($V(k) \geq 0$). The length of V is the number of servers K in the network.

OUTPUT

U	$U(k)$ is the utilization of center k .
R	$R(k)$ is the average response time at center k .
Q	$Q(k)$ is the average number of customers in center k .
X	$X(k)$ is the throughput of center k .
G	Normalization constants (vector). $G(n+1)$ corresponds to $G(n)$, as array indexes in Octave start from 1.

See also: qnconvolution.

REFERENCES

Herb Schwetman, *Some Computational Aspects of Queueing Network Models*, Technical Report CSD-TR-354, Department of Computer Sciences, Purdue University, feb, 1981 (revised). http://www.cs.purdue.edu/research/technical_reports/1980/TR%2080-354.pdf

M. Reiser, H. Kobayashi, *On The Convolution Algorithm for Separable Queueing Networks*, In Proceedings of the 1976 ACM SIGMETRICS Conference on Computer Performance Modeling Measurement and Evaluation (Cambridge, Massachusetts, United States, March 29–31, 1976). SIGMETRICS '76. ACM, New York, NY, pp. 109–117. <http://doi.acm.org/10.1145/800200.806187>

This implementation is based on G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998, pp. 313–317. Function `qnconvolutionld` is slightly different from the version described in Bolch et al. because it supports general load-dependent centers (while the version in the book does not). The modification is in the definition of function `F()` in `qnconvolutionld` which has been made similar to function f_i defined in Schwetman, *Some Computational Aspects of Queueing Network Models*.

6.3.3 Open networks

`[U, R, Q, X] = qnopensingle (lambda, S, V)` [Function File]
`[U, R, Q, X] = qnopensingle (lambda, S, V, m)` [Function File]
 Analyze open, single class BCMP queueing networks.

This function works for a subset of BCMP single-class open networks satisfying the following properties:

- The allowed service disciplines at network nodes are: FCFS, PS, LCFS-PR, IS (infinite server);

- Service times are exponentially distributed and load-independent;
- Service center i can consist of $m(i) \geq 1$ identical servers.
- Routing is load-independent

INPUTS

λ	Overall external arrival rate ($\lambda > 0$).
S	$S(k)$ is the average service time at center i ($S(k) > 0$).
V	$V(k)$ is the average number of visits to center k ($V(k) \geq 0$).
m	$m(k)$ is the number of servers at center i . If $m(k) < 1$, then service center k is a delay center (IS); otherwise it is a regular queueing center with $m(k)$ servers. Default is $m(k) = 1$ for each k .

OUTPUTS

U	If k is a queueing center, $U(k)$ is the utilization of center k . If k is an IS node, then $U(k)$ is the <i>traffic intensity</i> defined as $X(k) * S(k)$.
R	$R(k)$ is the average response time of center k .
Q	$Q(k)$ is the average number of requests at center k .
X	$X(k)$ is the throughput of center k .

See also: qnopen, qnclosed, qnvisits.

From the results computed by this function, it is possible to derive other quantities of interest as follows:

- **System Response Time:** The overall system response time can be computed as $R_s = \sum_{i=1}^K V_i R_i$
- **Average number of requests:** The average number of requests in the system can be computed as: $Q_s = \sum_{i=1}^K Q(i)$

EXAMPLE

```
lambda = 3;
V = [16 7 8];
S = [0.01 0.02 0.03];
[U R Q X] = qnopensingle( lambda, S, V );
R_s = dot(R,V) # System response time
N = sum(Q) # Average number in system
+ R_s = 1.4062
+ N = 4.2186
```

REFERENCES

G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998.

`[U, R, Q, X] = qnopenmulti (lambda, S, V)` [Function File]
`[U, R, Q, X] = qnopenmulti (lambda, S, V, m)` [Function File]

Exact analysis of open, multiple-class BCMP networks. The network can be made of *single-server* queueing centers (FCFS, LCFS-PR or PS) or delay centers (IS). This function assumes a network with K service centers and C customer classes.

S	$S(k)$ is the mean service time on server k ($S(k) > 0$).
V	$V(k)$ is the average number of visits to service center k ($V(k) \geq 0$).
m	$m(k)$ is the number of servers at center k . If $m(k) < 1$, center k is a delay center (IS); otherwise it is a regular queueing center (FCFS, LCFS-PR or PS) with $m(k)$ servers. Default is $m(k) = 1$ (each service center has a single server).
Z	External delay for customers ($Z \geq 0$). Default is 0.

OUTPUTS

U	If k is a FCFS, LCFS-PR or PS node, then $U(k)$ is the utilization of center k . If k is an IS node, then $U(k)$ is the <i>traffic intensity</i> defined as $X(k)*S(k)$.
R	$R(k)$ is the response time at center k . The system response time R_{sys} can be computed as $R_{sys} = N/X_{sys} - Z$
Q	$Q(k)$ is the average number of requests at center k . The number of requests in the system can be computed either as $\text{sum}(Q)$, or using the formula $N - X_{sys} * Z$.
X	$X(k)$ is the throughput of center k . The system throughput X_{sys} can be computed as $X_{sys} = X(1) / V(1)$
G	Normalization constants. $G(n+1)$ corresponds to the value of the normalization constant $G(n)$, $n = 0, 1, \dots, N$ as array indexes in Octave start from 1. $G(n)$ can be used in conjunction with the BCMP theorem to compute steady-state probabilities.

See also: qnclosedsinglemvad.

From the results provided by this function, it is possible to derive other quantities of interest as follows:

EXAMPLE

```

S = [ 0.125 0.3 0.2 ];
V = [ 16 10 5 ];
N = 20;
m = ones(1,3);
Z = 4;
[U R Q X] = qnclosedsinglemva(N,S,V,m,Z);
X_s = X(1)/V(1); # System throughput
R_s = dot(R,V); # System response time
printf("System throughput\t%f\n", X_s );
printf("System Response Time\t%f\n", R_s );
printf("Avg. number in system\t%f\n\n", N-X_s*Z );
printf("\t\tUtil\t\tQlen\t\tRes. time\tTput\n");
for k=1:length(S)
    printf("Device %d\t%f\t%f\t%f\t%f\n", k, U(k), Q(k), R(k), X(k) );
endfor

```

REFERENCES

M. Reiser and S. S. Lavenberg, *Mean-Value Analysis of Closed Multichain Queuing Networks*, Journal of the ACM, vol. 27, n. 2, April 1980, pp. 313–322. <http://doi.acm.org/10.1145/322186.322195>

This implementation is described in R. Jain, *The Art of Computer Systems Performance Analysis*, Wiley, 1991, p. 577. Multi-server nodes are treated according to G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998, Section 8.2.1, "Single Class Queueing Networks".

`[U, R, Q, X] = qnclosedsinglevald (N, S, V)` [Function File]
`[U, R, Q, X] = qnclosedsinglevald (N, S, V, Z)` [Function File]

Exact MVA algorithm for closed, single class queueing networks with load-dependent service centers. This function supports FCFS, LCFS-PR, PS and IS nodes. For networks with only fixed-rate service centers and multiple-server nodes, the function `qnclosedsinglemva` is more efficient.

INPUTS

- N Population size (number of requests in the system, $N > 0$).
- S $S(k, n)$ denotes the mean service time at server k where there are n requests at that center, $1 \leq n \leq N$ ($S(k, n) \geq 0$). S can be either a matrix or a function handle. If S is a function handle, it must support vector arguments (i.e., it must be possible to evaluate $S(k, n)$ with k and/or n being vectors).
- V $V(k)$ is the average number of visits to service center k ($V(k) \geq 0$).
- Z external delay ("think time", $Z \geq 0$); default 0.

OUTPUTS

- U $U(k)$ is the utilization of service center k . The utilization is defined as the probability that service center k is not empty, that is, $U_k = 1 - \pi_k(0)$ where $\pi_k(0)$ is the steady-state probability that there are 0 jobs at service center k .
- R $R(k)$ is the response time on service center k .
- Q $Q(k)$ is the average number of requests in service center k .
- X $X(k)$ is the throughput of service center k .

REFERENCES

M. Reiser and S. S. Lavenberg, *Mean-Value Analysis of Closed Multichain Queuing Networks*, Journal of the ACM, vol. 27, n. 2, April 1980, pp. 313–322. <http://doi.acm.org/10.1145/322186.322195>

This implementation is described in G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998, Section 8.2.4.1, "Networks with Load-Dependent Service: Closed Networks".

$[U, R, Q, X] = \text{qnclosedmultimva}(N, S, V)$ [Function File]
 $[U, R, Q, X] = \text{qnclosedmultimva}(N, S, V, m)$ [Function File]
 $[U, R, Q, X] = \text{qnclosedmultimva}(N, S, V, m, Z)$ [Function File]

Analyze closed, multiclass queueing networks with K service centers and C independent customer classes (chains) using the Mean Value Analysis (MVA) algorithm. Only fixed-rate service centers or multiple server nodes are supported. The number of requests in each class (chain) is fixed. Actually this implementation requires that each customer class is an independent chain.

Queueing policies at service centers can be any of the following:

FCFS (First-Come-First-Served) customers are served in order of arrival; multiple servers are allowed. For this kind of queueing discipline, average service times must be class-independent.

PS (Processor Sharing) customers are served in parallel by a single server, each customer receiving an equal share of the service rate.

LCFS-PR (Last-Come-First-Served, Preemptive Resume) customers are served in reverse order of arrival by a single server and the last arrival preempts the customer in service who will later resume service at the point of interruption.

IS (Infinite Server) customers are delayed independently of other customers at the service center (there is effectively an infinite number of servers).

INPUTS

N $N(c)$ is the number of class c requests in the system ($N(c) > 0$).

S $S(c, k)$ is the mean service time for class c customers at center k ($S(c, k) \geq 0$). If center k is a FCFS node ($m(k) > 1$), then the service times must be class-independent: $\text{all}(S(:, k) == S(1, k))$.

V $V(c, k)$ is the average number of visits of class c customers to service center k ($V(c, k) \geq 0$).

m If $m(k) < 1$, then center k is assumed to be a delay center (IS node $-/G/\infty$). If $m(k) == 1$, then service center k is a regular queueing center ($M/M/1$ -FCFS, $-/G/1$ -LCFS-PR or $-/G/1$ -PS). Finally, if $m(k) > 1$, center k is a $M/M/m$ -FCFS center with $m(k)$ identical servers. Default is $m(k) = 1$ for each k .

Z $Z(c)$ is the class c external delay (think time). Default is $Z(c) = 0$ for all c .

OUTPUTS

U If k is a FCFS, LCFS-PR or PS node, then $U(c, k)$ is the class c utilization at center k . If k is IS, then $U(c, k)$ is the class c traffic intensity at center k , defined as $U(c, k) = X(c, k) * S(c, k)$.

R $R(c, k)$ is the class c response time at service center k . The class c system response time can be computed as $\text{dot}(R, V, 2)$.

- Q $Q(c, k)$ is the average number of class c requests at center k . The total number of requests at center k is $\text{sum}(Q(:, k))$. The total number of class c requests in the system is $\text{sum}(Q(c, :))$.
- X $X(c, k)$ is the class c throughput at center k . The class c system throughput can be computed as $X(c, 1) / V(c, 1)$.

See also: qnclosed, qnclosedmultimvaapprox.

NOTE

Given a network with K service centers, C job classes and population vector $\mathbf{N} = (N_1, N_2, \dots, N_C)$, the MVA algorithm requires space $O(C \prod_i (N_i + 1))$. The time complexity is $O(CK \prod_i (N_i + 1))$. This implementation is slightly more space-efficient (see details in the code). While the space requirement can be mitigated by using some optimizations, the time complexity can not. If you need to analyze large closed networks you should consider the `qnclosedmultimvaapprox` function, which implements the approximate MVA algorithm. Note however that `qnclosedmultimvaapprox` will only provide approximate results.

REFERENCES

M. Reiser and S. S. Lavenberg, *Mean-Value Analysis of Closed Multichain Queuing Networks*, Journal of the ACM, vol. 27, n. 2, April 1980, pp. 313–322. <http://doi.acm.org/10.1145/322186.322195>

This implementation is based on G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998 and Edward D. Lazowska, John Zahorjan, G. Scott Graham, and Kenneth C. Sevcik, *Quantitative System Performance: Computer System Analysis Using Queueing Network Models*, Prentice Hall, 1984. <http://www.cs.washington.edu/homes/lazowska/qsp/>. In particular, see section 7.4.2.1 ("Exact Solution Techniques").

`[U, R, Q, X] = qnclosedmultimvaapprox (N, S, V)` [Function File]
`[U, R, Q, X] = qnclosedmultimvaapprox (N, S, V, m)` [Function File]
`[U, R, Q, X] = qnclosedmultimvaapprox (N, S, V, m, Z)` [Function File]
`[U, R, Q, X] = qnclosedmultimvaapprox (N, S, V, m, Z,` [Function File]
`epsilon)`
`[U, R, Q, X] = qnclosedmultimvaapprox (N, S, V, m, Z,` [Function File]
`epsilon, iter_max)`

Analyze closed, multiclass queueing networks with K service centers and C customer classes using the approximate Mean Value Analysis (MVA) algorithm.

This implementation uses Bard and Schweitzer approximation. It is based on the assumption that

$$Q_i(\mathbf{N} - \mathbf{1}_c) \approx \frac{n-1}{n} Q_i(\mathbf{N})$$

where \mathbf{N} is a valid population mix, $\mathbf{N} - \mathbf{1}_c$ is the population mix \mathbf{N} with one class c customer removed, and $n = \sum_c N_c$ is the total number of requests.

This implementation works for networks made of infinite server (IS) nodes and single-server nodes only.

INPUTS

N	$N(c)$ is the number of class c requests in the system ($N(c) > 0$).
S	$S(c, k)$ is the mean service time for class c customers at center k ($S(c, k) \geq 0$).
V	$V(c, k)$ is the average number of visits of class c requests to center k ($V(c, k) \geq 0$).
m	$m(k)$ is the number of servers at service center k . If $m(k) < 1$, then the service center k is assumed to be a delay center (IS). If $m(k) == 1$, service center k is a regular queueing center (FCFS, LCFS-PR or PS) with a single server node. If omitted, each service center has a single server. Note that multiple server nodes are not supported.
Z	$Z(c)$ is the class c external delay. Default is $Z(c) = 0$ for all c .
<i>epsilon</i>	Stopping tolerance (<i>epsilon</i> > 0). The algorithm stops if the queue length computed on two subsequent iterations are less than <i>epsilon</i> . Default is $1e - 5$.
<i>iter_max</i>	Maximum number of iterations (<i>iter_max</i> > 0, default is 100). The function aborts if convergence is not reached within the maximum number of iterations.

OUTPUTS

U	If k is a FCFS, LCFS-PR or PS node, then $U(c, k)$ is the utilization of class c requests on service center k . If k is an IS node, then $U(c, k)$ is the class c traffic intensity at device k , defined as $U(c, k) = X(c) * S(c, k)$
R	$R(c, k)$ is the response time of class c requests at service center k .
Q	$Q(c, k)$ is the average number of class c requests at service center k .
X	$X(c, k)$ is the class c throughput at service center k .

See also: qnclosed.

REFERENCES

Y. Bard, *Some Extensions to Multiclass Queueing Network Analysis*, proc. 4th Int. Symp. on Modelling and Performance Evaluation of Computer Systems, feb. 1979, pp. 51–62.

P. Schweitzer, *Approximate Analysis of Multiclass Closed Networks of Queues*, Proc. Int. Conf. on Stochastic Control and Optimization, jun 1979, pp. 25–29.

This implementation is based on Edward D. Lazowska, John Zahorjan, G. Scott Graham, and Kenneth C. Sevcik, *Quantitative System Performance: Computer System Analysis Using Queueing Network Models*, Prentice Hall, 1984. <http://www.cs.washington.edu/homes/lazowska/qsp/>. In particular, see section 7.4.2.2 ("Approximate Solution Techniques"). This implementation is slightly different from the one described above, as it computes the average response times R instead of the residence times.

6.3.5 Mixed Networks

$[U, R, Q, X] = \text{qnmix}(\lambda, N, S, V, m)$ [Function File]

Solution of mixed queueing networks through MVA. The network consists of K service centers (single-server or delay centers) and C independent customer chains. Both open and closed chains are possible. λ is the vector of per-chain arrival rates (open classes); N is the vector of populations for closed chains.

Note: In this implementation class switching is **not** allowed. Each customer class *must* correspond to an independent chain.

If the network is made of open or closed classes only, then this function calls `qnclosedmultimva` or `qnclosedmultimva` respectively, and prints a warning message.

INPUTS

λ

N For each customer chain c :

- if c is a closed chain, then $N(c) > 0$ is the number of class c requests and $\lambda(c)$ must be zero;
- If c is an open chain, $\lambda(c) > 0$ is the arrival rate of class c requests and $N(c)$ must be zero;

For each c , the following must hold:

$$(\lambda(c) > 0 \ \&\& \ N(c) == 0) \ || \ (\lambda(c) == 0 \ \&\& \ N(c) > 0)$$

which means that either $\lambda(c)$ is nonzero and $N(c)$ is zero, or the other way around. If for some c , $\lambda(c) \neq 0$ and $N(c) \neq 0$, an error is reported and this function aborts.

S $S(c, k)$ is the mean service time for class c customers on service center k , $S(c, k) \geq 0$. For FCFS nodes, service times must be class-independent.

V $V(c, k)$ is the average number of visits of class c customers to service center k ($V(c, k) \geq 0$).

m $m(k)$ is the number of servers at service center k . Only single-server ($m(k) == 1$) or IS (Infinite Server) nodes ($m(k) < 1$) are supported. If omitted, each service center is assumed to have a single server. Queueing discipline for single-server nodes can be FCFS, PS or LCFS-PR.

OUTPUTS

U $U(c, k)$ is the utilization of class c requests on service center k .

R $R(c, k)$ is the response time of class c requests on service center k .

Q $Q(c, k)$ is the average number of class c requests on service center k .

X $X(c, k)$ is the class c throughput on service center k .

See also: `qnclosedmultimva`, `qnclosedmultimva`, `qnclosedmultimva`.

REFERENCES

Edward D. Lazowska, John Zahorjan, G. Scott Graham, and Kenneth C. Sevcik, *Quantitative System Performance: Computer System Analysis Using Queueing Network Models*,

Prentice Hall, 1984. <http://www.cs.washington.edu/homes/lazowska/qsp/>. In particular, see section 7.4.3 ("Mixed Model Solution Techniques"). Note that in this function we compute the mean response time R instead of the mean residence time as in the reference.

Herb Schwetman, *Implementing the Mean Value Algorithm for the Solution of Queueing Network Models*, Technical Report CSD-TR-355, Department of Computer Sciences, Purdue University, feb 15, 1982, available at http://www.cs.purdue.edu/research/technical_reports/1980/TR%2080-355.pdf

6.4 Algorithms for non Product-Form QN

$[U, R, Q, X] = \text{qnmvablo}(K, S, M, P)$ [Function File]

MVA algorithm for closed queueing networks with blocking. `qnmvablo` computes approximate utilization, response time and mean queue length for closed, single class queueing networks with blocking.

INPUTS

K population size, i.e., number of requests in the system. K must be strictly greater than zero, and less than the overall network capacity: $K < \text{sum}(M)$.

S Average service time. $S(i)$ is the average service time requested on server i ($S(i) > 0$).

M Server capacity. $M(i)$ is the capacity of service center i . The capacity is the maximum number of requests in a service center, including the request currently in service ($M(i) > 1$).

P $P(i, j)$ is the probability that a request which completes service at server i will be transferred to server j .

OUTPUTS

U $U(i)$ is the utilization of service center i .

R $R(i)$ is the average response time of service center i .

Q $Q(i)$ is the average number of requests in service center i (including the request in service).

X $X(i)$ is the throughput of service center i .

See also: `qnclosed`, `qnclosed`.

REFERENCES

Ian F. Akyildiz, *Mean Value Analysis for Blocking Queueing Networks*, IEEE Transactions on Software Engineering, vol. 14, n. 2, april 1988, pp. 418–428. <http://dx.doi.org/10.1109/32.4663>

$[U, R, Q, X] = \text{qnmarkov}(\lambda, S, C, P)$ [Function File]

$[U, R, Q, X] = \text{qnmarkov}(\lambda, S, C, P, m)$ [Function File]

$[U, R, Q, X] = \text{qnmarkov}(N, S, C, P)$ [Function File]

$[U, R, Q, X] = \text{qnmarkov}(N, S, C, P, m)$ [Function File]

Compute utilization, response time, average queue length and throughput for open or closed queueing networks with finite capacity. Blocking type is Repetitive-Service

(RS). This function explicitly generates and solve the underlying Markov chain, and thus might require a large amount of memory.

More specifically, networks which can be analyzed by this function have the following properties:

- There exists only a single class of customers.
- The network has K service centers. Center i has $m_i > 0$ servers, and has a total (finite) capacity of $C_i \geq m_i$ which includes both buffer space and servers. The buffer space at service center i is therefore $C_i - m_i$.
- The network can be open, with external arrival rate to center i equal to λ_i , or closed with fixed population size N . For closed networks, the population size N must be strictly less than the network capacity: $N < \sum_i C_i$.
- Average service times are load-independent.
- P_{ij} is the probability that requests completing execution at center i are transferred to center j , $i \neq j$. For open networks, a request may leave the system from any node i with probability $1 - \sum_j P_{ij}$.
- Blocking type is Repetitive-Service (RS). Service center j is *saturated* if the number of requests is equal to its capacity C_j . Under the RS blocking discipline, a request completing service at center i which is being transferred to a saturated server j is put back at the end of the queue of i and will receive service again. Center i then processes the next request in queue. External arrivals to a saturated servers are dropped.

INPUTS

lambda

N If the first argument is a vector *lambda*, it is considered to be the external arrival rate $\lambda(i) \geq 0$ to service center i of an open network. If the first argument is a scalar, it is considered as the population size N of a closed network; in this case N must be strictly less than the network capacity: $N < \text{sum}(C)$.

S $S(i)$ is the average service time at service center i

C $C(i)$ is the Capacity of service center i . The capacity includes both the buffer and server space $m(i)$. Thus the buffer space is $C(i) - m(i)$.

P $P(i, j)$ is the transition probability from service center i to service center j .

m $m(i)$ is the number of servers at service center i . Note that $m(i) \geq C(i)$ for each i . If m is omitted, all service centers are assumed to have a single server ($m(i) = 1$ for all i).

OUTPUTS

U $U(i)$ is the utilization of service center i .

R $R(i)$ is the response time on service center i .

Q $Q(i)$ is the average number of customers in the service center i , *including* the request in service.

X $X(i)$ is the throughput of service center i .

Note:

The space complexity of this implementation is $O(\prod_{i=1}^K (C_i + 1)^2)$. The time complexity is dominated by the time needed to solve a linear system with $\prod_{i=1}^K (C_i + 1)$ unknowns.

6.5 Bounds on performance

$[Xu, Rl] = \text{qnopenab}(\lambda, D)$ [Function File]

Compute Asymptotic Bounds for single-class, open Queueing Networks with K service centers.

INPUTS

λ overall arrival rate to the system (scalar). Abort if $\lambda \leq 0$

D $D(k)$ is the service demand of service center k . Abort if $D(k) < 0$ for any k

OUTPUTS

Xu Upper bound on the system throughput.

Rl Lower bound on the system response time.

See also: qnopenbsb.

REFERENCES

Edward D. Lazowska, John Zahorjan, G. Scott Graham, and Kenneth C. Sevcik, *Quantitative System Performance: Computer System Analysis Using Queueing Network Models*, Prentice Hall, 1984. <http://www.cs.washington.edu/homes/lazowska/qsp/>. In particular, see section 5.2 ("Asymptotic Bounds").

$[Xl, Xu, Rl, Ru] = \text{qnclosedab}(N, D)$ [Function File]

$[Xl, Xu, Rl, Ru] = \text{qnclosedab}(N, D, Z)$ [Function File]

Compute Asymptotic Bounds for single-class, closed Queueing Networks with K service centers.

INPUTS

N number of requests in the system (scalar, $N > 0$).

D $D(k)$ is the service demand of service center k , $D(k) \geq 0$.

Z external delay (think time, scalar, $Z \geq 0$). If omitted, it is assumed to be zero.

OUTPUTS

Xl

Xu Lower and upper bound on the system throughput.

Rl

Ru Lower and upper bound on the system response time.

See also: qnclosedbsb, qnclosedgb, qnclosedpb.

REFERENCES

Edward D. Lazowska, John Zahorjan, G. Scott Graham, and Kenneth C. Sevcik, *Quantitative System Performance: Computer System Analysis Using Queueing Network Models*, Prentice Hall, 1984. <http://www.cs.washington.edu/homes/lazowska/qsp/>. In particular, see section 5.2 ("Asymptotic Bounds").

$[Xu, Rl, Ru] = \text{qnopenbsb}(\lambda, D)$ [Function File]

Compute Balanced System Bounds for single-class, open Queueing Networks with K service centers.

INPUTS

λ overall arrival rate to the system (scalar). Abort if $\lambda < 0$

D $D(k)$ is the service demand of service center k . Abort if $D(k) < 0$ for any k .

OUTPUTS

Xl Lower bound on the system throughput.

Rl

Ru Lower and upper bound on the system response time.

See also: qnopenab.

REFERENCES

Edward D. Lazowska, John Zahorjan, G. Scott Graham, and Kenneth C. Sevcik, *Quantitative System Performance: Computer System Analysis Using Queueing Network Models*, Prentice Hall, 1984. <http://www.cs.washington.edu/homes/lazowska/qsp/>. In particular, see section 5.4 ("Balanced Systems Bounds").

$[Xl, Xu, Rl, Ru] = \text{qnclosedbsb}(N, D)$ [Function File]

$[Xl, Xu, Rl, Ru] = \text{qnclosedbsb}(N, D, Z)$ [Function File]

Compute Balanced System Bounds for single-class, closed Queueing Networks with K service centers.

INPUTS

N number of requests in the system (scalar).

D $D(k)$ is the service demand of service center k . Abort if $D(k) < 0$ for any k .

Z external delay (think time, scalar) experienced by requests. If omitted, it is assumed to be zero.

OUTPUTS

Xl

Xu Lower and upper bound on the system throughput.

Rl

Ru Lower and upper bound on the system response time.

See also: qnclosedab, qnclosedgb, qnclosedpb.

`[Xl, Xu] = qnclosedpb (N, D)` [Function File]
 Compute PB Bounds for single-class, closed Queueing Networks with K service centers.

INPUTS

N number of requests in the system (scalar). Must be $N > 0$.
 D $D(k)$ is the service demand of service center k . Must be $D(k) \geq 0$ for all k .
 Z external delay (think time, scalar). If omitted, it is assumed to be zero. Must be $Z \geq 0$.

OUTPUTS

Xl
 Xu Lower and upper bound on the system throughput.

See also: qnclosedab, qbclosedbsb, qnclosedgb.

REFERENCES

The original paper describing PB Bounds is C. H. Hsieh and S. Lam, *Two classes of performance bounds for closed queueing networks*, PEVA, vol. 7, no. 1, pp. 3–30, 1987

This function implements the non-iterative variant described in G. Casale, R. R. Muntz, G. Serazzi, *Geometric Bounds: a Non-Iterative Analysis Technique for Closed Queueing Networks*, IEEE Transactions on Computers, 57(6):780-794, June 2008.

`[Xl, Xu, Ql, Qu] = qnclosedgb (N, D, Z)` [Function File]
 Compute Geometric Bounds (GB) for single-class, closed Queueing Networks.

INPUTS

N number of requests in the system (scalar, $N > 0$).
 D $D(k)$ is the service demand of service center k ($D(k) \geq 0$).
 Z external delay (think time, scalar). If omitted, it is assumed to be zero.

OUTPUTS

Xl
 Xu Lower and upper bound on the system throughput. If $Z > 0$, these bounds are computed using *Geometric Square-root Bounds* (GSB). If $Z = 0$, these bounds are computed using *Geometric Bounds* (GB)

Ql
 Qu $Ql(i)$ and $Qu(i)$ are the lower and upper bounds respectively of the queue length for service center i .

See also: qnclosedab.

REFERENCES

G. Casale, R. R. Muntz, G. Serazzi, *Geometric Bounds: a Non-Iterative Analysis Technique for Closed Queueing Networks*, IEEE Transactions on Computers, 57(6):780-794, June 2008. <http://doi.ieeecomputersociety.org/10.1109/TC.2008.37>

In this implementation we set X^+ and X^- as the upper and lower Asymptotic Bounds as computed by the `qnclosedab` function, respectively.

6.6 Utility functions

6.6.1 Open or closed networks

`[U, R, Q, X] = qnclosed(N, S, V, ...)` [Function File]

MVA algorithm for closed queueing networks. The network can be made of fixed-capacity centers or delay centers; load-dependent service centers are also supported. N is the population (number of requests) in the system.

- If N is a scalar, the exact MVA algorithm for single-class closed networks is used. If S is a vector, then $S(k)$ is the average service time of service center k , and this function uses the `qnclosedsinglemv` algorithm for load-independent service centers. If S is a matrix, $S(k,i)$ is the average service time at service center k when $i > 0$ jobs are present; in this case, this function uses the `qnclosedsinglemvld` function for load-dependent service centers.
- If N is a vector, the exact MVA algorithm for multiclass networks is used, as implemented by the `qnclosedmultimva` function.

See also: `qnclosedsinglemv`, `qnclosedsinglemvld`, `qnclosedmultimva`.

EXAMPLE

```
P = [0 0.3 0.7; 1 0 0; 1 0 0]; # Transition probability matrix
S = [1 0.6 0.2]; # Average service times
m = ones(1,3); # All centers are single-server
Z = 2; # External delay
Nmax = 15; # Maximum population to consider

V = qnvisits(P); # Compute number of visits from P
D = V .* S; # Compute service demand from S and V
X_bsb_lower = X_bsb_upper = zeros(1,Nmax);
X_ab_lower = X_ab_upper = zeros(1,Nmax);
X_mva = zeros(1,Nmax);
for n=1:Nmax
    [X_bsb_lower(n) X_bsb_upper(n)] = qnclosedbsb(n, D, Z);
    [X_ab_lower(n) X_ab_upper(n)] = qnclosedab(n, D, Z);
    [U R Q X] = qnclosed( n, S, V, m, Z );
    X_mva(n) = X(1)/V(1);
endfor
close all;
plot(1:Nmax, X_ab_lower,"g;Asymptotic Bounds;", \
     1:Nmax, X_bsb_lower,"k;Balanced System Bounds;", \
     1:Nmax, X_mva,"b;MVA;", "linewidth", 2, \
     1:Nmax, X_bsb_upper,"k", \
     1:Nmax, X_ab_upper,"g" );
title("MVA vs Balanced System Bounds");
axis([1,Nmax,0,1]);
xlabel("Request Population Size N");
ylabel("System Throughput X(N)");
legend("location","southeast");
```

`[U, R, Q, X] = qnopen (lambda, S, V, ...)` [Function File]

Compute utilization, response time, average number of requests in the system, and throughput for open queueing networks. If *lambda* is a scalar, the network is considered a single-class QN and is solved using `qnopensingle`. If *lambda* is a vector, the network is considered as a multiclass QN and solved using `qnopenmulti`.

See also: `qnopensingle`, `qnopenmulti`.

6.6.2 Computation of the visit counts

For closed, single-class networks the number of visits satisfies the following conditions:

$$V_j = \sum_{i=1}^N V_i P_{ij}, \quad V_1 = 1$$

while for open networks with arrival rates $\lambda(i)$:

$$V_j = \lambda_j + \sum_{i=1}^N V_i P_{ij}$$

where N is the dimension (number of rows or columns) of P .

`V = qnvisits (P)` [Function File]

`V = qnvisits (P, lambda)` [Function File]

Compute the average number of visits to the service centers of a single class, open or closed Queueing Network with N service centers.

INPUTS

P $P(i, j)$ is the probability that a request which completes service at service center i will be transferred to server j . It must hold that `all(all(P ≥ 0))`. For closed networks additionally it must hold that `sum(P, 2) == 1`.

lambda (for open networks only) external arrival vector. $\lambda(i)$ is the external arrival rate to service center i . If this parameter is omitted, the network is assumed to be closed.

OUTPUTS

V $V(i)$ is the average number of visits to server i .

EXAMPLE

```
P = [ 0 0.4 0.6 0; \
      0.2 0 0.2 0.6; \
      0 0 0 1; \
      0 0 0 0 ];
lambda = [0.1 0 0 0.3];
V = qnvisits(P, lambda);
S = [2 1 2 1.8];
m = [3 1 1 2];
[U R Q X] = qnopensingle( sum(lambda), S, V, m );
```

6.6.3 Other utility functions

`pop_mix = population_mix (k, N)` [Function File]

Return the set of valid population mixes with exactly k customers, for a closed multiclass Queueing Network with population vector N . More specifically, given a multiclass

Queueing Network with C customer classes, such that there are $N(i)$ requests of class i , a k -mix is a C -dimensional vector with the following properties:

```
all( mix >= 0 );
all( mix <= N );
sum( mix ) == k;
```

This function enumerates all valid k -mixes, such that $pop_mix(i)$ is a C dimensional row vector representing a valid population mix, for all i .

INPUTS

k Total population size (scalar) of the requested mix.
 N $N(i)$ is the number of class i requests. It must be $k \leq \text{sum}(N)$.

OUTPUTS

pop_mix $pop_mix(i,j)$ is the number of class j requests in the i -th population mix. The number of population mixes is $\text{rows}(pop_mix)$.

Note that if you are interested in the number of k -mixes and you don't care to enumerate them, you can use the function `qnmvpop`.

See also: `qnmvpop`.

REFERENCES

Herb Schwetman, *Implementing the Mean Value Algorithm for the Solution of Queueing Network Models*, Technical Report CSD-TR-355, Department of Computer Sciences, Purdue University, feb 15, 1982, available at http://www.cs.purdue.edu/research/technical_reports/1980/TR_80-355.pdf

Note that the slightly different problem of generating all tuples k_1, k_2, \dots, k_N such that $\sum_i k_i = k$ for some fixed k has been described in S. Santini, *Computing the Indices for a Complex Summation*, unpublished report, available at http://arantxa.ii.uam.es/~ssantini/writing/notes/s668_summation.pdf

$H = \text{qnmvpop}(N)$ [Function File]

Given a network with C customer classes, this function computes the number of valid population mixes $H(\mathbf{r}, \mathbf{n})$ that can be constructed by the multiclass MVA algorithm by allocating n customers to the first r classes.

INPUTS

N Population vector. $N(c)$ is the number of class- c requests in the system. The total number of requests in the network is $\text{sum}(N)$.

OUTPUTS

H $H(\mathbf{r}, \mathbf{n})$ is the number of valid populations that can be constructed allocating n customers to the first r classes.

See also: `qnclosedmultimva, population_mix`.

REFERENCES

Zahorjan, J. and Wong, E. *The solution of separable queueing network models using mean value analysis*. SIGMETRICS Perform. Eval. Rev. 10, 3 (Sep. 1981), 80-85. DOI <http://doi.acm.org/10.1145/1010629.805477>

Appendix A Contributing Guidelines

Contributions and bug reports are *always* welcome. If you want to contribute to the `qnetworks` package, here are some guidelines you should consider:

- If you are contributing a new function, please embed proper documentation within the function itself. The documentation must be in `texinfo` format, so that it will be extracted and formatted into the printable manual. See the existing functions of the `qnetworks` package for the documentation style.
- The documentation should be as precise as possible. In particular, always state what the valid ranges of the parameters are.
- If you are contributing a new function, ensure that the function properly checks the validity of its input parameters. For example, each function accepting vectors should check whether the dimensions match.
- Always provide bibliographic references for each algorithm you contribute. If your implementation differs in some way from the reference you give, please describe how and why your implementation differs.
- Include Octave test and demo blocks with your code. Test blocks are particularly important, because Queueing Network algorithms tend to be quite complex to implement correctly, and we must ensure that the implementations provided with the `qnetworks` package are (mostly) correct.

Send your contribution to Moreno Marzolla (marzolla@cs.unibo.it).

Appendix B Acknowledgements

The following people (listed in alphabetical order) contributed to the `qnetworks` package, either by providing feedback, reporting bugs or contributing code: Philip Carinhas, Dmitry Kolesnikov.

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Version 3, 29 June 2007

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